# A $d^{1/2+o(1)}$ Monotonicity Tester for Boolean Functions on *d*-Dimensional Hypergrids

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**FOCS 2023** 

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# Monotonicity Testing

- We consider  $f: [n]^d \rightarrow \{0,1\}$
- f is monotone if  $f(x) \le f(y)$  whenever  $x \prec y$
- Partial order:  $x \leq y$  iff  $x_i \leq y_i, \forall i \in [d]$

Given 
$$f: [n]^d \rightarrow \{0,1\}$$
 and  $\varepsilon > 0...$   
1. if  $f$  monotone: **accept** w.p. >  
2. if  $\varepsilon(f) > \varepsilon$ : **reject** w.p. >

\* Non-adaptive queries

A central problem in property testing proposed by Goldreich-Goldwasser-Lehman-Ron-Samorodnitsky 99

**Distance to monotonicity:**  

$$\varepsilon(f) = n^{-d} \cdot \min_{\substack{h \text{ monotone}}} \# x \colon f(x) \neq h(x)$$

![](_page_1_Figure_8.jpeg)

![](_page_1_Picture_9.jpeg)

## Abridged History of Non-adaptive Testing (for brevity let $\varepsilon = \Omega(1)$ )

The Hypercube (n = 2)

Khot-Minzer-Safra  $\widetilde{O}(d^{1/2})$ FOCS 15

The **Hypergrid** ( $n \ge 2$ )  $\approx \sqrt{}$ 

Dodis-Goldreich-Lehman-Raskhodnikova-Ron-Samorodnitsky 99 and Berman-Raskhodnikova-Yaroslavtsev 14

Black-Chakrabarty-Seshadhri SODA 18, 20

Braverman-Khot-Kindler-Minzer ITCS 23,

Black-Chakrabarty-Seshadhri STOC 23

Black-Chakrabarty-Seshadhri FOCS 23

Chen-Waingarten-Xie STOC 17

$$\widetilde{\Omega}(d^{1/2})$$

O(d)

![](_page_2_Figure_11.jpeg)

$$\widetilde{O}(d^{5/6})$$

 $\widetilde{O}(\mathsf{poly}(n) \cdot d^{1/2})$ 

 $d^{1/2+o(1)}$ 

![](_page_2_Figure_15.jpeg)

3

# The Hypercube: a (very) brief history

![](_page_3_Figure_1.jpeg)

(0,0,0)

### The Edge Tester

Edge tester (GGLRS [99])

- Sample an edge (*x*, *y*)
- Reject if f(x) > f(y).

How many decreasing edges are there when  $\varepsilon(f) > \varepsilon$ ?

![](_page_4_Figure_5.jpeg)

**Theorem:** (GGLRS [99])  $I_f^- \ge \Omega(\varepsilon(f))$ 

 $\implies$  # decreasing edges  $\geq \Omega(\varepsilon(f)) \cdot 2^d$ 

Total # edges is  $d \cdot 2^{d-1}$ 

 $\implies$  Edge test succeeds with probability  $\Omega(\varepsilon/d)$ 

 $\implies$  Repeat  $O(d/\varepsilon)$  times!

![](_page_4_Figure_11.jpeg)

![](_page_4_Figure_12.jpeg)

**Theorem:** (Poincaré)  $I_f \ge \Omega(var(f))$ 

Question: Is this a tight analysis of the edge tester?

![](_page_4_Picture_15.jpeg)

### The Path Tester

**Theorem:** GGLRS [99]  $I_f^- \ge \Omega(\varepsilon(f))$ 

• To beat O(d) requires something other than the edge tester

Path tester (CS [14])

- Sample  $x \prec y$  which differ on  $\approx d^{1/2}$  bits
- Reject if f(x) > f(y)
- We succeed with probability  $\Omega(d^{-1/2})$  Why? for the anti-dictator function **spread**

**Theorem:** Talagrand [93]  $\mathbb{E}_{x}[I_{f}(x)^{1/2}] = \Omega(var(f))$ 

![](_page_5_Picture_8.jpeg)

### Is this inequality tight? Yes.

### anti-dictator function: $f(x) = 1 - x_1$

$$\epsilon(f) = 1/2 \text{ and } I_f^- = 1/2$$

![](_page_5_Figure_12.jpeg)

• Why? Decreasing edges are **spread** amongst the vertices

Question:

Is there a more nuanced way to understand boundary?

![](_page_5_Picture_16.jpeg)

Can test with  $\widetilde{O}(d^{1/2})$ queries by combining edge tester and path tester

# The Hypergrid

![](_page_6_Figure_1.jpeg)

The (fully augmented) hypergrid:

DAG with...

- Vertex set:  $[n]^d$
- Edges: (*x*, *y*) which differ on 1 coordinate **by any value**

**Thresholded Influence:** 

![](_page_7_Figure_4.jpeg)

$$\mathbb{E}_{x}[\Phi_{f}(x)^{1/2}] = \Omega\left(\frac{\varepsilon(f)}{\log n}\right)$$

• When 
$$n = 2$$
,  $\Phi_f(x) = I_f^-(x)$ 

![](_page_7_Picture_7.jpeg)

Generalizes the directed Talagrand inequality by KMS

How does this inequality help us analyze monotonicity testers?

![](_page_7_Picture_11.jpeg)

### **Good Subgraphs** (let's assume $\varepsilon(f) = \Omega(1)$ )

**Theorem (BCS STOC 23):** For any 
$$f: [n]^d \to \mathbb{E}_x[\Phi_f(x)^{1/2}] = \Omega\left(\frac{\varepsilon(f)}{\log n}\right)$$

Good subgraph lemma (KMS 15, informal):

For some  $\Delta$ , there is bipartite subgraph of decreasing edges G(U, V, E) with max degree  $\Delta$  and  $|E| \ge \widetilde{\Omega}(\sqrt{\Delta} \cdot n^d)$ 

$$\Delta = d \qquad \Longrightarrow \qquad |E|$$

$$\Delta = 1 \qquad \Longrightarrow \qquad |E|$$

![](_page_8_Figure_6.jpeg)

 $|E| \ge \Omega(\sqrt{d} \cdot n^d)$ 

### $\geq \Omega(n^d)$ and *E* is a **matching**

![](_page_8_Picture_10.jpeg)

### Plan for the Rest of the Talk

**Matching assumption:**  $f: [n]^d \rightarrow \{0,1\}$ 

There is a matching *E* of  $\Omega(n^d)$  decreasing edges

- 1) An  $O(n\sqrt{d})$  tester under matching assumption
  - These techniques are due to KMS 15

2) Sketch for  $O(\log n\sqrt{d})$  tester under matching assumption

- We may assume n = poly(d) and so  $O(\log n\sqrt{d}) = O(\sqrt{d})$ (BCS SODA 20, Harms-Yoshida ICALP 22)

![](_page_9_Figure_8.jpeg)

![](_page_9_Picture_10.jpeg)

### An $O(n\sqrt{d})$ Query Tester

**Assumption:** There is a matching *E* of  $\Omega(n^d)$  decreasing edges

![](_page_10_Figure_2.jpeg)

**Def**:  $y \in [n]^d$  is **persistent** if a random walk from y of length  $\tau - 1$  leads to z with f(z) = f(y) with probability  $\geq 0.9$ 

 $\mathbb{P}[f]$ 

Lemma (KMS, informal): If # decreasing edges  $< n\sqrt{d} \cdot n^d$ , then # nonpersistent points is  $o(n^d)$ 

All endpoints of *E* are **persistent** 

$$\mathbb{P}[f(x) = 1 \land f(y) = 0]$$

$$\geq \sum_{(u,u+se_i)\in E} \mathbb{P}[x = u] \cdot \mathbb{P}[T \ni i] \qquad \mathbb{P}[y_i - x_i = s] \cdot \mathbb{P}[f(y) = 0.9]$$

$$\geq \Omega(n^{-1}d^{-1/2})$$
End of the story for constant *n*... What about

larger *n*?

![](_page_10_Picture_9.jpeg)

![](_page_10_Picture_10.jpeg)

11

### **Internal Points**

**Assumption:** There is a matching *E* of  $\Omega(n^d)$  decreasing edges

• Let I(u, v) = interval of points between u and v

... let's assume I(u, v) is at least half 0's for all  $(u, v) \in E$ 

Walk distribution 2:

- Sample *x* u.a.r. and  $T \subseteq [d]$  of  $\tau \approx \sqrt{d}$  random coordinates
  - For  $i \in T$ , choose  $p \in [\log n]$  u.a.r
    - set  $y_i \in [x_i, x_i + 2^p]$  u.a.r

Walk 2 analysis: condition on passing through u.a.r  $z \in I(u, v)$ 

$$\approx \log^{-1} n$$

![](_page_11_Figure_10.jpeg)

![](_page_11_Picture_12.jpeg)

### **Red Edges and the Shifted Path Test**

**Assumption:** There is a matching *E* of  $\Omega(n^d)$  decreasing edges

**Def**: Call *z* mostly-zero-below (mzb) if a  $(\tau - 1)$ -length downward random walk from z ends at a 0 with prob.  $\geq 0.9$ 

**Def**: Call an edge (u, v) red if a  $(\tau - 1)$ -length upward random walk from a u.a.r.  $w \in I(u, v)$  ends at z which is **mzb** with prob.  $\geq 0.01$ 

Recall: All endpoints of E are **persistent** 

*E* is mostly red  $\implies$  Upward walk + downward shift finds a violation with prob.  $\Omega(d^{-1/2}\log^{-1}n)$ 

![](_page_12_Figure_6.jpeg)

What if E is mostly not red?

![](_page_12_Figure_10.jpeg)

## Non-red Edges

**Assumption:** There is a matching *E* of  $\Omega(n^d)$  decreasing edges

**Def**: Call an edge (u, v) red if a  $(\tau - 1)$ -length upward random walk from a u.a.r.  $w \in I(u, v)$  ends at z which is **mzb** with prob.  $\geq 0.01$ 

(u, v) non-red  $\implies z$  mostly-one-below with prob.  $\geq 0.99$ 

Recall: *u*, *v* are **persistent** 

Consider (u', v') a random translation of (u, v)

![](_page_13_Picture_6.jpeg)

With high prob. f(u') = 1, f(v') = 0 and most of I(u', v') is **mostly-one-below** 

![](_page_13_Picture_8.jpeg)

**Def**: Call an edge (u', v') blue if a constant fraction of I(u', v') is mostly-one-below

![](_page_13_Figure_10.jpeg)

![](_page_13_Figure_11.jpeg)

A downward random walk from v' discovers a violation with probability  $\Omega(d^{-1/2}\log^{-1}n)$ 

# **Red-blue Win-win Argument**

**Assumption:** There is a matching *E* of  $\Omega(n^d)$  decreasing edges

**Def**: Call an edge (u, v) red if a  $(\tau - 1)$ -length upward random walk from a u.a.r.  $w \in I(u, v)$  ends at z which is **mzb** with prob.  $\geq 0.01$ 

**Def**: Call an edge (u', v') blue if a constant fraction of I(u', v') is mob

Case 1: *E* is mostly **red** 

⇒ Upward walk + downward shift finds a violation with prob.  $\Omega(d^{-1/2}\log^{-1}n)$ 

![](_page_14_Figure_7.jpeg)

# **Red-blue Win-win Argument**

**Assumption:** There is a matching *E* of  $\Omega(n^d)$  decreasing edges

**Def**: Call an edge (u, v) red if a  $(\tau - 1)$ -length upward random walk from a u.a.r.  $w \in I(u, v)$  ends at z which is mzb with prob.  $\geq 0.01$ 

**Def**: Call an edge (u', v') **blue** if a constant fraction of I(u', v') is **mob** 

Case 1: *E* is mostly **red** 

 $\implies$  Upward walk + downward shift finds a violation with prob.  $\Omega(d^{-1/2}\log^{-1}n)$ 

Case 2: *E* is mostly **non-red** 

 $\implies$  Flow argument: there exists another matching E' which is mostly **blue** 

 $\implies$  **Downward walk** finds a violation with prob.  $\Omega(d^{-1/2}\log^{-1}n)$ 

![](_page_15_Figure_9.jpeg)

![](_page_16_Figure_0.jpeg)

Chen-Waingarten-Xie 17  $\overline{\Omega}(d^{1/3})$ 

Khot-Minzer-Safra 15  $\widetilde{O}(d^{1/2})$ 

![](_page_16_Picture_5.jpeg)